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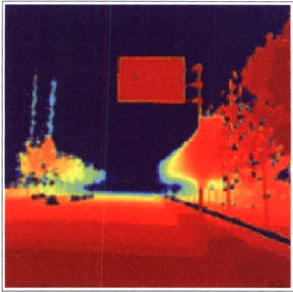
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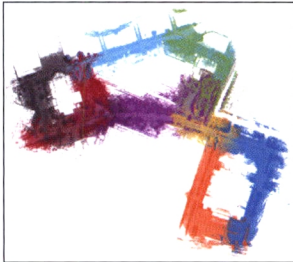
“自动驾驶技术与应用”专刊



面向智能驾驶的平行视觉感知：基本概念、框架与应用
(第0067页)



Edge-guided GAN：边界信息引导的深度图像修复
(第0186页)



利用边缘计算的多车协同激光雷达SLAM(第0218页)

序言 王飞跃，张云泉 I
编者按 II

综述
面向智能驾驶测试的仿真场景构建技术综述
任秉韬，邓伟文，白雪松，李江坤，纵瑞雪，朱冰，丁娟 0001
自动驾驶软件测试技术研究综述
冯洋，夏志龙，郭安，陈振宇 0013
强化学习的自动驾驶控制技术研究进展
潘峰，鲍泓 0028
自动驾驶地图的数据标准比较研究
詹骄，郭迟，雷婷婷，屈宜琪，吴杭彬，刘经南 0036
视觉感知的端到端自动驾驶运动规划综述
刘旒菲，胡学敏，陈国文，刘士豪，陈龙 0049

平行驾驶
面向智能驾驶的平行视觉感知：基本概念、框架与应用
李轩，王飞跃 0067
平行视觉的基本框架与关键算法
张慧，李轩，王飞跃 0082

目标检测与跟踪
自动驾驶场景的尺度感知实时行人检测
徐钦恺，马岩，钱旭，张龔 0093
实时视觉目标跟踪与视频对象分割多任务框架
李瀚，刘坤华，刘嘉杰，张晓晔 0101
提升预测框定位稳定性的视频目标检测
郝腾龙，李熙莹 0113
道路结构特征下的车道线智能检测
张翔，唐小林，黄岩军 0123
适用全速域大曲率路径的自动驾驶跟踪算法
张龔，郑颖，鲍泓 0135
伪3D卷积神经网络与注意力机制结合的疲劳驾驶检测
庄员，戚湧 0143
基于眼部自商图—梯度图共生矩阵的疲劳驾驶检测
潘剑凯，柳政卿，王秋成 0154

自动驾驶场景感知与仿真
结合局部平面参数预测的无监督单目图像深度估计
周大可，田径，杨欣 0165
深度纯追随的拟人化无人驾驶转向控制模型
单云霄，黄润辉，何泽，龚志豪，景民，邹雪松 0176
Edge-guided GAN：边界信息引导的深度图像修复
刘坤华，王雪辉，谢玉婷，胡坚耀 0186
引入概率分布的深度神经网络贪婪剪枝
胡骏，黄启鹏，刘嘉昕，刘威，袁淮，赵宏 0198

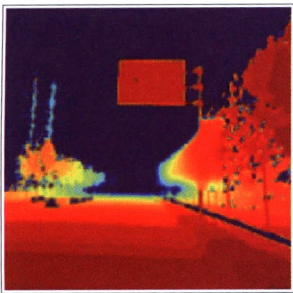
高精地图构建与SLAM
开放道路中匹配高精度地图的在线相机外参标定
廖文龙，赵华卿，严骏驰 0208
利用边缘计算的多车协同激光雷达SLAM
崔明月，钟仕鹏，刘思瑶，李博洋，吴成昊，黄凯 0218

CONTENTS

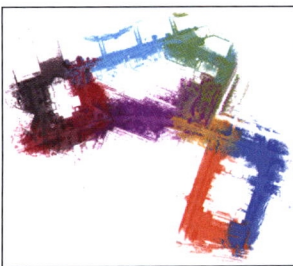
JOURNAL OF IMAGE AND GRAPHICS



Parallel visual perception for intelligent driving: basic concept, framework and application (P0067)



Edge-guided GAN: a depth image inpainting approach guided by edge information (P0186)



Cooperative LiDAR SLAM for multi-vehicles based on edge computing (P0218)

Review

Technologies of virtual scenario construction for intelligent driving testing	
Ren Bingtao, Deng Weiwen, Bai Xuesong, Li Jiangkun, Zong Ruixue, Zhu Bing, Ding Juan	0001
Survey of testing techniques of autonomous driving software	
Feng Yang, Xia Zhilong, Guo An, Chen Zhenyu	0013
Research progress of automatic driving control technology based on reinforcement learning	
Pan Feng, Bao Hong	0028
Comparative study on data standards of autonomous driving map	
Zhan Jiao, Guo Chi, Lei Tingting, Qu Yiqi, Wu Hangbin, Liu Jingnan	0036
Review of end-to-end motion planning for autonomous driving with visual perception	
Liu Yifei, Hu Xuemin, Chen Guowen, Liu Shihao, Chen Long	0049

Parallel Driving

Parallel visual perception for intelligent driving: basic concept, framework and application	
Li Xuan, Wang Feiyue	0067
The basic framework and key algorithms of parallel vision	
Zhang Hui, Li Xuan, Wang Feiyue	0082

Object Detection and Tracking

Scale-aware EfficientDet: real-time pedestrian detection algorithm for automated driving	
Xu Xinkai, Ma Yan, Qian Xu, Zhang Yan	0093
Multitask framework for video object tracking and segmentation combined with multi-scale inter-frame information	
Li Han, Liu Kunhua, Liu Jiajie, Zhang Xiaoye	0101
Video object detection method for improving the stability of bounding box	
Hao Tenglong, Li Xiyang	0113
Intelligent detection of lane based on road structure characteristics	
Zhang Xiang, Tang Xiaolin, Huang Yanjun	0123
Autonomous vehicle tracking algorithm for high curvature path in full speed range	
Zhang Yan, Zheng Ying, Bao Hong	0135
Driving fatigue detection based on pseudo 3D convolutional neural network and attention mechanisms	
Zhuang Yuan, Qi Yong	0143
Fatigue driving detection based on ocular self-quotient image and gradient image co-occurrence matrix	
Pan Jiankai, Liu Zhengqing, Wang Qiucheng	0154

Scene Perception and Simulation of Autonomous Driving

Unsupervised monocular image depth estimation based on the prediction of local plane parameters	
Zhou Dake, Tian Jing, Yang Xin	0165
Human-like steering model for autonomous driving based on deep pure pursuit method	
Shan Yunxiao, Huang Runhui, He Ze, Gong Zhihao, Jing Min, Zou Xuesong	0176
Edge-guided GAN: a depth image inpainting approach guided by edge information	
Liu Kunhua, Wang Xuehui, Xie Yuting, Hu Jianyao	0186
Greedy pruning of deep neural networks fused with probability distribution	
Hu Jun, Huang Qipeng, Liu Jiaxin, Liu Wei, Yuan Huai, Zhao Hong	0198

High-Definition Map Construction and SLAM

Online extrinsic camera calibration based on high-definition map matching on public roadway	
Liao Wenlong, Zhao Huaqing, Yan Junchi	0208
Cooperative LiDAR SLAM for multi-vehicles based on edge computing	
Cui Mingyue, Zhong Shipeng, Liu Siyao, Li Boyang, Wu Chenghao, Huang Kai	0218

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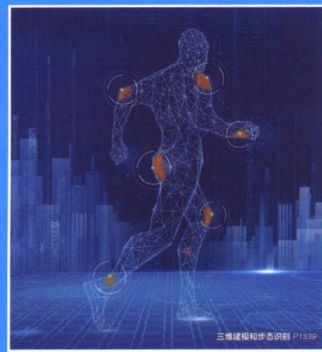
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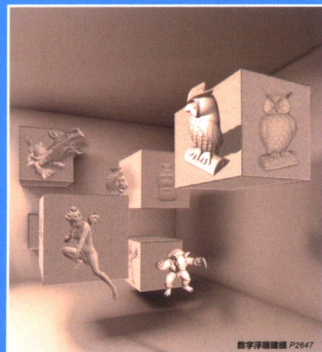
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